

A Posteriori Error Analysis of the Method of Characteristics

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Differential Equation

$$\begin{aligned} \partial_t u - \operatorname{div}(d\nabla u) + \mathbf{a} \cdot \nabla u + ru &= f && \text{in } \Omega \times (0, T] \\ u &= 0 && \text{on } \Gamma \times (0, T] \\ u &= u_0 && \text{in } \Omega \end{aligned}$$

- ▶ $d > 0$
- ▶ $r \geq 0$
- ▶ $\mathbf{a} \in C^1(\Omega \times (0, T])^d$
- ▶ $\operatorname{div} \mathbf{a} = 0$ in $\Omega \times (0, T]$
- ▶ $\mathbf{a} = 0$ on $\Gamma \times (0, T]$

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Norms

- ▶ Energy norm

$$\|v\| = \{d\|\nabla v\|^2 + r\|v\|^2\}^{\frac{1}{2}}$$

- ▶ Dual norm

$$\|\varphi\|_* = \sup_{v \in H_0^1(\Omega) \setminus \{0\}} \frac{\langle \varphi, v \rangle}{\|v\|}$$

- ▶ Error norm

$$\|u\|_{X(a,b)} = \left\{ \operatorname{ess. sup}_{t \in (a,b)} \|u(\cdot, t)\|^2 + \int_a^b \|u(\cdot, t)\|^2 dt + \int_a^b \|(\partial_t u + \mathbf{a} \cdot \nabla u)(\cdot, t)\|_*^2 dt \right\}^{\frac{1}{2}}$$

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Method of Characteristics

- ▶ For every $(x^*, t^*) \in \Omega \times (0, T]$ the **characteristic equation**

$$\begin{aligned} \frac{d}{dt} x(t; x^*, t^*) &= \mathbf{a}(x(t; x^*, t^*), t), && t \in (0, t^*), \\ x(t^*; x^*, t^*) &= x^* \end{aligned}$$

admits a unique global solution.

- ▶ Set $U(x^*, t) = u(x(t; x^*, t^*), t)$.
- ▶ Then

$$d_t U - \operatorname{div}(d\nabla U) + ru = f \quad \text{in } \Omega \times (0, T).$$

- ▶ Discretize $d_t U$ by backward differences and spatial derivatives by standard finite elements.

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Meshes and Spaces

- ▶ $\mathcal{I} = \{(t_{n-1}, t_n] : 1 \leq n \leq N_{\mathcal{I}}\}$ partition of $[0, T]$.
- ▶ $\tau_n = t_n - t_{n-1}$.
- ▶ \mathcal{T}_n , $0 \leq n \leq N_{\mathcal{I}}$, affine equivalent, admissible, shape regular partitions of Ω .
- ▶ **Transition condition:** There is a common refinement $\tilde{\mathcal{T}}_n$ of \mathcal{T}_n and \mathcal{T}_{n-1} such that $h_K \leq ch_{K'}$ for all $K \in \mathcal{T}_n$ and all $K' \in \tilde{\mathcal{T}}_n$ with $K' \subset K$.
- ▶ $V_n \subset H_0^1(\Omega)$ finite element space corresponding to \mathcal{T}_n .
- ▶ **Lagrange condition:** Functions in V_n are uniquely determined by their values in a set \mathcal{V}_n of nodes.

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Discrete Problem

- ▶ Set $u_{\mathcal{T}_0}^0 = \pi_0 u_0$.
- ▶ For $n = 1, \dots, N_{\mathcal{I}}$:
 - ▶ Compute an approximation x_z^{n-1} to $x(t_{n-1}; z, t_n)$ for every $z \in \mathcal{V}_{n,\Omega}$.
 - ▶ Compute $\tilde{u}_{\mathcal{T}_n}^{n-1} \in V_n$ such that

$$\tilde{u}_{\mathcal{T}_n}^{n-1}(z) = \begin{cases} u_{\mathcal{T}_{n-1}}^{n-1}(x_z^{n-1}) & \text{if } z \in \mathcal{V}_{n,\Omega}, \\ 0 & \text{if } z \in \mathcal{V}_{n,\Gamma}. \end{cases}$$

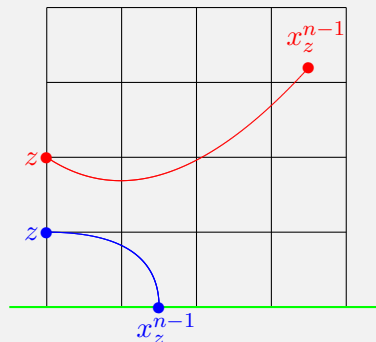
- ▶ Find $u_{\mathcal{T}_n}^n \in V_n$ such that

$$\left(\frac{u_{\mathcal{T}_n}^n - \tilde{u}_{\mathcal{T}_n}^{n-1}}{\tau_n}, v_{\mathcal{T}_n} \right) + (d\nabla u_{\mathcal{T}_n}^n, \nabla v_{\mathcal{T}_n}) + (ru_{\mathcal{T}_n}^n, v_{\mathcal{T}_n}) = (f, v_{\mathcal{T}_n})$$

holds for all $v_{\mathcal{T}_n} \in V_n$.

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Re-interpolation



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Basic Steps

- ▶ Error and residual are equivalent.
- ▶ The residual splits into a spatial and a temporal residual. The norm of the sum of these is equivalent to the sum of their norms.
- ▶ Derive a reliable, efficient and robust error indicator for the temporal residual.
- ▶ Derive a reliable, efficient and robust error indicator for the spatial residual.

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Equivalence of Error and Residual

- ▶ $u_{\mathcal{I}}$ continuous piece-wise affine, equals $u_{\mathcal{I}_n}^n$ at t_n .
- ▶ Residual:

$$\begin{aligned} \langle R(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d\nabla u_{\mathcal{I}}, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{I}}, v) - (ru_{\mathcal{I}}, v) \end{aligned}$$

- ▶ Lower bound:

$$\|R(u_{\mathcal{I}})\|_{L^2(t_{n-1}, t_n; H^{-1}(\Omega))} \leq \sqrt{2} \|u - u_{\mathcal{I}}\|_{X(t_{n-1}, t_n)}$$

- ▶ Upper bound:

$$\|u - u_{\mathcal{I}}\|_{X(0, t_n)} \leq \left\{ 4\|u_0 - \pi_0 u_0\|^2 + 6\|R(u_{\mathcal{I}})\|_{L^2(0, t_n; H^{-1}(\Omega))}^2 \right\}^{\frac{1}{2}}$$

Proof of the Equivalence

- ▶ Relation of residual and error:

$$\langle R(u_{\mathcal{I}}), v \rangle = (\partial_t e, v) - (\mathbf{a} \cdot \nabla e, v) - (d\nabla e, \nabla v) - (re, v)$$

- ▶ Lower bound: Definition of primal and dual norm plus Cauchy-Schwarz inequality.
- ▶ Upper bound: Parabolic energy estimate with $v = e$ as test-function.

Decomposition of the Residual

- ▶ Temporal residual:

$$\begin{aligned} \langle R_{\tau}(u_{\mathcal{I}}), v \rangle &= (d\nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}}), v) \\ &\quad + (r(u_{\mathcal{I}_n}^n - u_{\mathcal{I}}), v) \end{aligned}$$

- ▶ Spatial residual:

$$\begin{aligned} \langle R_h(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d\nabla u_{\mathcal{I}_n}^n, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{I}_n}^n, v) - (ru_{\mathcal{I}_n}^n, v) \end{aligned}$$

- ▶ Splitting: $R(u_{\mathcal{I}}) = R_{\tau}(u_{\mathcal{I}}) + R_h(u_{\mathcal{I}})$
- ▶ Estimate for $L^2(t_{n-1}, t_n; H^{-1}(\Omega))$ -norms:

$$\begin{aligned} \frac{1}{5} \left\{ \|R_{\tau}(u_{\mathcal{I}})\|^2 + \|R_h(u_{\mathcal{I}})\|^2 \right\}^{\frac{1}{2}} &\leq \|R_{\tau}(u_{\mathcal{I}}) + R_h(u_{\mathcal{I}})\| \\ &\leq \|R_{\tau}(u_{\mathcal{I}})\| + \|R_h(u_{\mathcal{I}})\| \end{aligned}$$

Motivation of the Lower Bound

- ▶ Strengthened Cauchy-Schwarz inequality for $v = c$ and $w = \frac{b-t}{b-a}$:

$$\int_a^b v w = \frac{1}{2} c (b-a) = \frac{\sqrt{3}}{2} \|v\|_{(a,b)} \|w\|_{(a,b)}$$

- ▶ Hence:

$$\|v + w\|_{(a,b)}^2 \geq \left(1 - \frac{\sqrt{3}}{2}\right) \left\{ \|v\|_{(a,b)}^2 + \|w\|_{(a,b)}^2 \right\}$$

Proof of the Lower Bound

- ▶ $R_h(u_{\mathcal{I}})$ is piece-wise constant.
- ▶ $R_{\tau}(u_{\mathcal{I}})$ is piece-wise affine: $R_{\tau}(u_{\mathcal{I}}) = \frac{t_n-t}{\tau_n} \rho^n$ with

$$\langle \rho^n, v \rangle = (d\nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}), v) + (r(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}), v).$$

- ▶ Choose $v, w \in H_0^1(\Omega)$ such that

$$\begin{aligned} \|v\| &= \|R_h(u_{\mathcal{I}})\|_*, & \langle R_h(u_{\mathcal{I}}), v \rangle &= \|R_h(u_{\mathcal{I}})\|_*^2, \\ \|w\| &= \|\rho^n\|_*, & \langle \rho^n, w \rangle &= \|\rho^n\|_*^2. \end{aligned}$$

- ▶ Insert $3\left(\frac{t-t_{n-1}}{\tau_n}\right)^2 v + \frac{t_n-t}{\tau_n} w$ as test-function in representation of $R(u_{\mathcal{I}})$.

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Estimation of the Temporal Residual

- ▶ Recall $R_{\tau}(u_{\mathcal{I}}) = \frac{t_n-t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d\nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}), v). \end{aligned}$$

- ▶ Upper bound:

$$\|\rho^n\|_* \leq \left\{ \|u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}\| + \|\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1})\|_* \right\}$$

- ▶ Follows from definition of ρ^n and $\|\cdot\|_*$.

- ▶ Lower bound:

$$\frac{1}{3} \left\{ \|u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}\| + \|\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1})\|_* \right\} \leq \|\rho^n\|_*$$

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Proof of the Lower Bound

- ▶ Set $w^n = u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}$ and choose $v \in H_0^1(\Omega)$ with $\|v\| = \|\mathbf{a} \cdot \nabla w^n\|_*$ and $(\mathbf{a} \cdot \nabla w^n, v) = \|\mathbf{a} \cdot \nabla w^n\|_*^2$
- ▶ Insert $\frac{1}{2}w^n + \frac{1}{2}v$ in the definition of ρ^n :

$$\begin{aligned} &\langle \rho^n, \frac{1}{2}w^n + \frac{1}{2}v \rangle \\ &= \underbrace{\frac{1}{2}(d\nabla w^n, \nabla w^n) + \frac{1}{2}(r w^n, w^n)}_{=\frac{1}{2}\|w^n\|^2} + \underbrace{\frac{1}{2}(\mathbf{a} \cdot \nabla w^n, w^n)}_{=0} \\ &\quad + \underbrace{\frac{1}{2}(d\nabla w^n, \nabla v) + \frac{1}{2}(r w^n, v)}_{\geq -\frac{1}{2}\|w^n\| \|\mathbf{a} \cdot \nabla w^n\|_*} + \underbrace{\frac{1}{2}(\mathbf{a} \cdot \nabla w^n, v)}_{=\frac{1}{2}\|\mathbf{a} \cdot \nabla w^n\|_*^2} \end{aligned}$$

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Estimation of the Convective Derivative I.

- ▶ Assume that $\|\mathbf{a}\|_{\infty} \leq c_d$.
- ▶ Friedrichs' inequality implies

$$\begin{aligned} (\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}), v) &\leq \|\mathbf{a}\|_{\infty} \|\nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1})\| \|v\| \\ &\leq \|\mathbf{a}\|_{\infty} \|\nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1})\| c_{\Omega} \|\nabla v\| \end{aligned}$$

- ▶ Hence $\|\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1})\|_* \leq c_c c_{\Omega} \|u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}\|$ and $\|\mathbf{a} \cdot \nabla(u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1})\|_*$ is equivalent to $\|u_{\mathcal{I}_n}^n - u_{\mathcal{I}_{n-1}}^{n-1}\|$.

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Estimation of the Convective Derivative II.

- ▶ Assume that $\|\mathbf{a}\|_\infty \gg d$.
- ▶ Consider the auxiliary problem

$$d(\nabla v_{\mathcal{T}_n}^n, \nabla \varphi) + r(v_{\mathcal{T}_n}^n, \varphi) = (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \varphi) \quad (*)$$

with variational and discrete solutions Φ and $\varphi_{\mathcal{T}_n}$.

- ▶ Then $\|\Phi\| = \|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$,
 $\|\varphi_{\mathcal{T}_n}\| \leq \|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$ and therefore

$$\begin{aligned} \frac{1}{3} \{ \|\varphi_{\mathcal{T}_n}\| + \|\Phi - \varphi_{\mathcal{T}_n}\| \} &\leq \|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_* \\ &\leq \|\varphi_{\mathcal{T}_n}\| + \|\Phi - \varphi_{\mathcal{T}_n}\|. \end{aligned}$$

- ▶ Transition condition implies that $\|\Phi - \varphi_{\mathcal{T}_n}\|$ is equivalent to every robust, i.e. residual, error indicator η_τ^n for (*).
- ▶ Hence $\|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$ is equivalent to $\|\varphi_{\mathcal{T}_n}\| + \eta_\tau^n$.

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Estimation of the Spatial Residual

- ▶ $R_h(u_{\mathcal{I}})$ does not satisfy the Galerkin orthogonality, but

$$\langle R_h(u_{\mathcal{I}}), v_{\mathcal{T}_n} \rangle = \left(\frac{u_{\mathcal{T}_n}^{n-1} - \tilde{u}_{\mathcal{T}_n}^{n-1}}{\tau_n} - \mathbf{a} \cdot \nabla u_{\mathcal{T}_n}^n, v_{\mathcal{T}_n} \right).$$

- ▶ Consider the auxiliary problem

$$d(\nabla w_{\mathcal{T}_n}^n, \nabla \varphi) + r(w_{\mathcal{T}_n}^n, \varphi) = \left(\frac{u_{\mathcal{T}_n}^{n-1} - \tilde{u}_{\mathcal{T}_n}^{n-1}}{\tau_n} - \mathbf{a} \cdot \nabla u_{\mathcal{T}_n}^n, \varphi \right) \quad (\#)$$

with variational and discrete solutions Ψ and $\psi_{\mathcal{T}_n}$.

- ▶ Then $\|\Psi\| = \|R_h(u_{\mathcal{I}})\|_*$, $\|\psi_{\mathcal{T}_n}\| \leq \|R_h(u_{\mathcal{I}})\|_*$ and
 $\frac{1}{3} \{ \|\psi_{\mathcal{T}_n}\| + \|\Psi - \psi_{\mathcal{T}_n}\| \} \leq \|R_h(u_{\mathcal{I}})\|_* \leq \|\psi_{\mathcal{T}_n}\| + \|\Psi - \psi_{\mathcal{T}_n}\|$.
- ▶ Transition condition implies that $\|\Psi - \psi_{\mathcal{T}_n}\|$ is equivalent to every robust, i.e. residual, error indicator η_h^n for (#).
- ▶ Hence $\|R_h(u_{\mathcal{I}})\|_*$ is equivalent to $\|\psi_{\mathcal{T}_n}\| + \eta_h^n$.

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Computation of η_h^n




- ▶ Want to replace $\tilde{u}_{\mathcal{T}_n}^{n-1}$ by $u_{\mathcal{T}_{n-1}}^{n-1}$.
- ▶ Integration by parts element-wise yields:

$$\begin{aligned} \langle R_h(u_{\mathcal{I}}), \varphi \rangle &= d(\nabla w_{\mathcal{T}_n}^n, \nabla \varphi) - r(w_{\mathcal{T}_n}^n, \varphi) \\ &= \sum_{K \in \mathcal{T}_n} \int_K \left(f - \frac{u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}}{\tau_n} + \operatorname{div}(d \nabla u_{\mathcal{T}_n}^n) \right. \\ &\quad \left. - \mathbf{a} \cdot \nabla u_{\mathcal{T}_n}^n - r u_{\mathcal{T}_n}^n + d \Delta w_{\mathcal{T}_n}^n - r w_{\mathcal{T}_n}^n \right) \varphi \\ &\quad + \sum_{E \in \mathcal{E}_n} \int_E \mathbb{J}_E(\mathbf{n}_E \cdot (d \nabla u_{\mathcal{T}_n}^n) - d \mathbf{n}_E \cdot \nabla w_{\mathcal{T}_n}^n) \varphi. \end{aligned}$$

- ▶ η_h^n consists of element and face residuals with weighting factors $\min\{d^{-\frac{1}{2}} h_K, r^{-\frac{1}{2}}\}$ and $d^{-\frac{1}{4}} \min\{d^{-\frac{1}{2}} h_K, r^{-\frac{1}{2}}\}^{\frac{1}{2}}$.

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